

# Hierarchical Bayesian modelling of exposure at default for revolving credit facilities

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Credit Scoring & Credit Control XVI

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# Outline

- 1 Some background on the problem.
- 2 The data used for model fitting/testing. We use Barclays' view of GCD data.
- 3 Model specifications. Reparameterisation, sampling from posterior and predictive distributions.
- 4 Results. Model selection. Comparison with Tobit model.
- 5 Discussion and future work.



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# Introduction

- Exposure at default (EAD) is an estimate of the exposure against a facility upon default of an obligor.
- EAD feeds into the calculation of RWA.
- CRR refers to credit conversion factors (CCF), the proportion of available headroom drawn between observation and default.
- By definition we have  $EAD = B_0 + CCF(L_0 - B_0)$ , where  $B_0$  and  $L_0$  are the balance and limit at observation.
- Banks with advanced permissions can model their own CCF (CRR Article 166).
- The time horizon for EAD estimates is one year (SS11/13 14.11).
- Estimates for EAD must be no less than current drawings, hence  $CCF \geq 0$ .
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## Our Approach

- Modelling CCF directly is challenging due to instability caused by small/zero headroom, i.e. when  $L_0 - B_0 < \epsilon$ .
- EAD typically exhibits very long tails. Modelling Usage at Default,  $UAD = EAD/L_0$ , means estimates are default weighted and not exposure weighted. Referred to as the *momentum* approach.
- We consider a zero-one inflated beta regression model for CCF.
- We shift and scale the beta-distributed random variable to obtain a parametric distribution for UAD.
- This enables us to model UAD directly but also constrains the implicit modelled values for CCF to the unit interval, ensuring that  $UAD \geq B_0/L_0 := \text{Usage Before Default (UBD)}$ .
- We introduce a margin of conservatism by centering the prior distribution for mean CCF on the standardised value of 75%.
- Models are implemented in the probabilistic programming language `stan` which provides efficient MCMC sampling from the joint posterior distribution of the model parameters.

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## Data Sources

- We source Corp & FI data from GCD.
- We clean the data keeping only facilities where:
  - there is positive headroom,
  - balance at default is greater than one year prior,
  - balance at default does not exceed limit one year prior.
- This leaves 521 facilities for modelling (summarised in Table →). Note Long tails.
- We source GDP data for different regions (description below ↓).

**Table:** Observed summary statistics for Balance 1yprd, CCF and EAD

	Balance 1yprd	CCF	EAD
Min.	0	0.000	0
1st Qu.	0	0.032	2031
Median	49	0.516	188518
Mean	3336193	0.501	5094438
3rd Qu.	702088	0.997	2755172
Max.	125296671	1.000	143903572

**Table:** Description of macro-economic variables used for modelling

Region	Source	Description
UK	ONS	U.K.: Gross Domestic Product, Current Prices (SA, Y/Y % chg)
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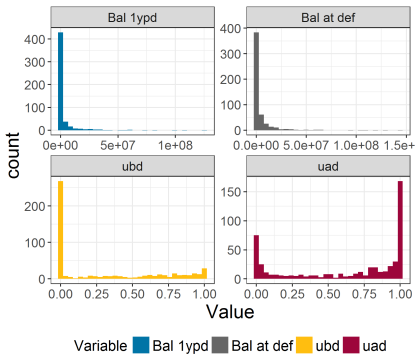
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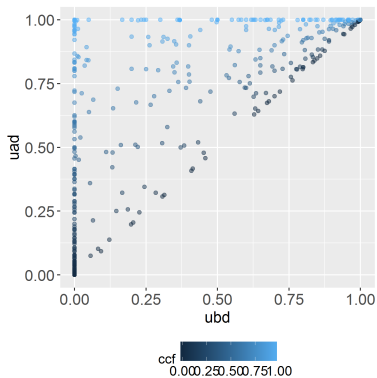
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## We calibrate the model to UAD



**Figure:** Histograms of Balance at one year prior to default, balance at default, UBD and UAD



**Figure:** UAD against UBD. Lighter coloured circles indicate higher CCF.

## Potential Model Drivers

- We define classes for CCF:  $(0, 0.5]$ ,  $(0.5, 1)$ , one and zero.
- The table shows average UBD, UAD and GDP by CCF class.
- Data indicates that UBD is on average higher for larger values of CCF.
- Mean GDP is on average higher where CCF is one compared to when CCF is zero.

**Table:** Mean UBD, UAD and GBP by CCF class: continuous in  $(0, 0.5]$ ,  $(0.5, 1)$ , one or zero

CCF class	Count	mean UBD	mean UAD	mean GDP
$(0,0.5]$	164	0.216	0.344	1.940
$(0.5,1)$	143	0.373	0.867	2.302
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## Model Parameterisation - Mixture of Beta and Binomial

- We follow Ospina and Ferrari (2012) and induce zero-one inflation via a mixture of Bernoulli and beta distributions.
- Letting  $y = CCF$ , the density for  $y$  is

$$f_{CCF}(y; \mu, \phi, \pi, \theta) = \pi Ber(\theta) + (1 - \pi) Beta(\mu, \phi)$$

- Parameters  $\pi$  and  $\theta$  represent

$$\pi = P(y \in \{0, 1\})$$

$$\theta = P(y = 1 | y \in \{0, 1\})$$

- These are related to  $p_0 = P(y = 0)$  and  $p_1 = P(y = 1)$  as follows:

$$\begin{aligned} p_0 &= P(y = 0 | y \in \{0, 1\})P(y \in \{0, 1\}) + P(y = 0 | y \in (0, 1))P(y \in (0, 1)) \\ &= (1 - \theta)\pi \end{aligned}$$

$$\begin{aligned} p_1 &= P(y = 1 | y \in \{0, 1\})P(y \in \{0, 1\}) + P(y = 1 | y \in (0, 1))P(y \in (0, 1)) \\ &= \theta\pi. \end{aligned}$$

- We recover  $\pi$  if we compute  $p_0 + p_1$ .

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## Model Parameterisation - Mixture of Beta and Binomial

- We follow Ospina and Ferrari (2012) and induce zero-one inflation via a mixture of Bernoulli and beta distributions.
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## Marginal Expectations

- The parameter  $\mu$  represents the conditional expectation of  $CCF$  given  $CCF$  is in the open unit interval.

$$\mu = E\{CCF|CCF \in (0, 1)\}$$

- The marginal expectation of  $CCF$  is

$$\begin{aligned} E(CCF) &= E(CCF|CCF = 0)P(CCF = 0) + \\ &E(CCF|CCF \in (0, 1))P(CCF \in (0, 1)) + \\ &E(CCF|CCF = 1)P(CCF = 1) \\ &= \mu(1 - \pi) + \theta\pi \end{aligned}$$

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## Likelihood and Prior Distributions

- We regress each model parameter on a set of covariates via a suitable link function and give vague prior distributions to the regression coefficients:

$$\mu = \text{inv\_logit}(x_i^\mu \beta^\mu), \quad \beta^\mu \sim N(0, 10^4 I)$$

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- The complete set of model parameters is  $\Omega = (\mu, \phi, \pi, \theta, \beta)$  where  $\beta = (\beta^\mu, \beta^\phi, \beta^\pi, \beta^\theta)$ .
- The likelihood function can be written as

$$L(\Omega; UAD, UBD) = \prod_{i=1}^n \{(1 - \theta_i) \pi_i\}^{\mathbb{I}(UAD_i = UBD_i)} (\theta_i \pi_i)^{\mathbb{I}(UAD_i = 1)} \times \\ \{(1 - \pi) \text{Beta}(UBD_i, 1)(\mu_i, \phi_i)\}^{\mathbb{I}(UBD_i < UAD_i < 1)}.$$

- Strictly, the likelihood is a function of  $\mu, \phi, \pi, \theta$  only through  $\beta$  via the deterministic link functions. However, on occasion we will model one or more of  $\mu, \phi, \pi, \theta$  directly.

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## Posterior Distributions

- The posterior distribution for  $\Omega$  is given by

$$f(\Omega|UAD, UBD) \propto L(\Omega; UAD, UBD)f(\Omega)$$

- Given  $N$  post burn-in samples from  $f(\Omega|UAD, UBD)$  the estimates for  $CCF_i$  and  $UAD_i$  are calculated as follows:

$$\widehat{CCF}_i = \frac{1}{N} \sum_{t=1}^N \mu_i^{(t)}(1 - \pi_i^{(t)}) + \theta_i^{(t)} \pi_i^{(t)}$$

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- We can obtain 95% credible interval from the samples  $CCF^{(t)}$  and  $UAD^{(t)}$ .
- For readability, change notation to let  $y = UAD$  and  $x = UBD$ .
- Prediction for out-of-sample data  $y_0 = UAD_0$ , requires sampling from the posterior predictive distribution.

$$f(y_0|x_0, y, x) = \int f(y_0|x_0, \Omega)f(\Omega|y, x)d\Omega$$

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- Given  $N$  post burn-in samples from  $f(\Omega|UAD, UBD)$  the estimates for  $CCF_i$  and  $UAD_i$  are calculated as follows:

$$\widehat{CCF}_i = \frac{1}{N} \sum_{t=1}^N \mu_i^{(t)}(1 - \pi_i^{(t)}) + \theta_i^{(t)} \pi_i^{(t)}$$

$$\widehat{UAD}_i = \frac{1}{N} \sum_{t=1}^N UBD_i + (1 - UBD_i) \{ \mu_i^{(t)}(1 - \pi_i^{(t)}) + \theta_i^{(t)} \pi_i^{(t)} \}$$

- We can obtain 95% credible interval from the samples  $CCF^{(t)}$  and  $UAD^{(t)}$ .
- For readability, change notation to let  $y = UAD$  and  $x = UBD$ .
- Prediction for out-of-sample data  $y_0 = UAD_0$ , requires sampling from the posterior predictive distribution.

$$f(y_0|x_0, y, x) = \int f(y_0|x_0, \Omega)f(\Omega|y, x)d\Omega$$

- If  $\Omega^{(t)} \sim f(\Omega|y, x)$  then  $y_0^{(t)} \sim f(y_0|x_0, \Omega^{(t)})$  is a draw from the posterior predictive distribution  $f(y_0|x_0, y, x)$ .

## Candidate models

- We look at different regression models for the parameters using available covariates UBD and GDP.
- Where we do not have a regression model for a parameter, we estimate it directly rather than through  $\beta_0$ . For example, we do not place a regression model on  $\pi$ , instead the prior is  $\pi \sim U(0, 1)$ .
- We use the notation  $\mu(ubd, gdp)$  to indicate that we model  $\mu = \text{inv\_logit}(\beta_0 + \beta_1 ubd + \beta_2 gdp)$ .
- A benchmark model for UAD is the Tobit model:
  - The Tobit model assumes a normal distribution but only observed for the unit interval. Point masses at zero and one.
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## Model Selection Results

- Models are fit to 80% of the data, holding out 20% for testing.
- Inference is based on 3000 post burn-in samples generated from three parallel MCMC chains.
- Model performance is judged by WAIC (widely-applicable IC), which is appropriate for Bayesian analysis (Watanabe, 2010), and prediction RMSE.
- The best performing model is M7 with  $\mu(ubd)$ ,  $\theta(gdp)$ .
- The best Tobit model has  $\mu(ubd, gdp)$ ,  $\sigma^2(ubd, gdp)$  where  $\sigma^2$  is modelled via a log-link.

Table: WAIC and RMSE for a selection of models

Model	Description	WAIC	RMSE
M1	$\mu(ubd)$	892.1	0.341
M2	$\mu(gdp)$	906.6	0.348
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M5	$\theta(gdp)$	895.7	0.340
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## Parameter Estimates for Best Model

Table: Parameter estimates for Model M7:  $\mu(ubd)$ ,  $\theta(gdp)$

parameter	mean	sd	2.5%	97.5%	$\hat{R}$
$\mu(\beta_0)$	-0.066	0.079	-0.221	0.096	0.999
$\mu(\beta_1)$	0.326	0.092	0.145	0.513	0.999
$\phi$	1.066	0.048	0.977	1.170	0.999
$\pi$	0.398	0.025	0.353	0.448	0.999
$\theta(\beta_0)$	0.426	0.170	0.101	0.756	1.002
$\theta(\beta_1)$	-0.578	0.166	-0.921	-0.281	0.999

- $\mu(\beta_1)$  indicates a significant correlation between the logit of conditional expectation of CCF and UBD.
- $\theta(\beta_1)$  indicates that GDP is a driver for  $\theta$  and hence  $p_0$  and  $p_1$ .
- $\hat{R}$  is an estimate of the potential scale reduction factor which is a well-known convergence statistic. Values below 1.1 are used to indicate convergence of the Markov chain to the posterior distribution of the parameter. (Gelman and Rubin, 1992).

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## Box plots of facility-level effects

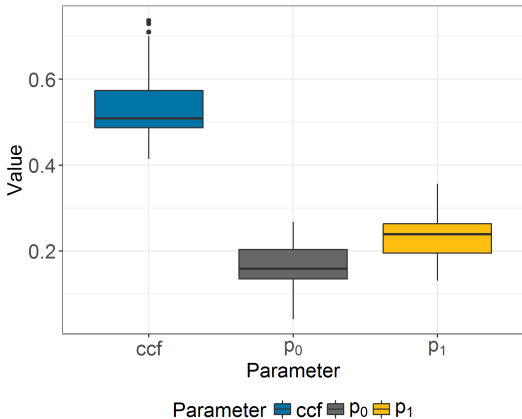


Figure: Boxplots of parameter estimates for  $CCF$ ,  $p_0$  and  $p_1$  for model M7

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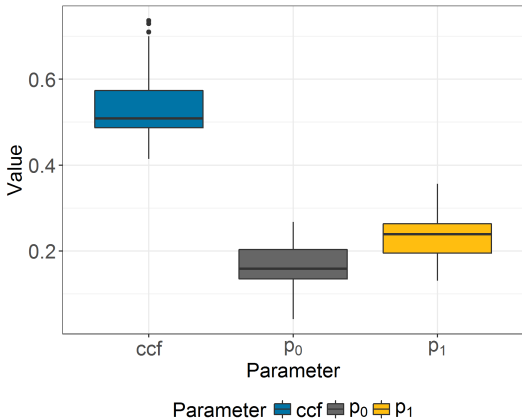


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## Conservative Prior Distribution

- We embed conservatism by adjusting the prior distribution for the conditional mean of CCF,  $\mu$ .
- For the preferred model we have  $\mu = \text{inv\_logit}(\beta_0 + \beta_1 UBD)$ , where  $\beta_k \sim N(m_k, v_k)$  for  $k = 0, 1$ .
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 $m_0 = \text{logit}(0.75) = \log(0.75/(1 - 0.75)) = \log(3)$ .
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- Re-arranging gives prior standard deviation  $\sqrt{v_0} = m_0/\Phi^{-1}(\alpha/2)$ .
- All modelled CCF values receive an uplift. With 95% confidence ( $\alpha = 5\%$ ) the average uplift is 1%, 99% confidence gives 1.5%.
- Strong prior belief does not strongly effect inference as the data overwhelms the prior.

Table: Parameter estimates Regulatory model

parameter	mean	sd	2.5%	97.5%	$\hat{R}$
$\mu(\beta_0)$	-0.042	0.081	-0.201	0.107	0.999
$\mu(\beta_1)$	0.332	0.094	0.159	0.514	0.999
$\phi$	1.062	0.049	0.968	1.160	0.999
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$\mu(\beta_1)$	0.332	0.094	0.159	0.514	0.999
$\phi$	1.062	0.049	0.968	1.160	0.999
$\pi$	0.400	0.025	0.352	0.450	1.001
$\theta(\beta_0)$	0.486	0.158	0.177	0.796	0.999
$\theta(\beta_1)$	-0.573	0.172	-0.908	-0.253	0.999



## Conservative Prior Distribution

- We embed conservatism by adjusting the prior distribution for the conditional mean of CCF,  $\mu$ .
- For the preferred model we have  $\mu = \text{inv\_logit}(\beta_0 + \beta_1 UBD)$ , where  $\beta_k \sim N(m_k, v_k)$  for  $k = 0, 1$ .
- We set  $m_0$  so that the prior mean is equal to the standardised value of 75%  
 $m_0 = \text{logit}(0.75) = \log(0.75/(1 - 0.75)) = \log(3)$ .
- We set  $v_0$  so that the  $\beta_0$  is significantly different from 0,  $P(\beta_0 < 0) = \alpha/2$ , where  $\alpha$  is 1 - confidence level, the strength of belief in the standardised value.
- Re-arranging gives prior standard deviation  $\sqrt{v_0} = m_0/\Phi^{-1}(\alpha/2)$ .
- All modelled CCF values receive an uplift. With 95% confidence ( $\alpha = 5\%$ ) the average uplift is 1%, 99% confidence gives 1.5%.
- Strong prior belief does not strongly effect inference as the data overwhelms the prior.**

Table: Parameter estimates Regulatory model

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- We have described a fully Bayesian approach to modelling EAD.
- This properly accounts for uncertainty in parameter estimation when predicting new values.
- By shifting and scaling a beta distribution we build a parametric regression model for UAD.
- We show how the prior distribution can be used to embed conservatism into model predictions.

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## Future Work

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- Full k-fold cross-validation.
- Wider model comparison.
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## References

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## stan

- **stan** is a probabilistic programming language providing efficient MCMC sampling from posterior distributions.
- There are 6 blocks: functions, data, parameters, model, transformed parameters and generated quantities.

---

```
functions {
  real generalised_beta_log_pdf(real y, real p, real q, real a) {
    return beta_lpdf(y | p, q) + (p - 1)*(log(y - a) - log(y)) - pow(1 - a, p + q - 1);
  }
  ...
}
data {
  int n;
  vector[n] x; //ubd
  vector<lower=0, upper=1>[n] y; //uad
  ...
}
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# stan

---

```
transformed parameters {
  vector<lower=0>[n] p;          // scale 1 of beta(p,q)
  p = mu * phi;
  ...
}
model {
  Pi ~ uniform(0, 1); coef_theta ~ normal(0, sqrt(10000));
  coef_mu ~ normal(0, sqrt(10000)); phi ~ lognormal(0, sqrt(10000));
  for (i in 1:n) { // zero-one inflated beta likelihood
    if (y[i] == x[i]) {
      target += log(Pi) + log1m(theta[i]);
    } else if (y[i] == 1) {
      target += log(Pi) + log(theta[i]);
    } else {
      target += log1m(Pi) + generalised_beta_log_pdf(y[i] , p[i], q[i], x[i]);
    }
  }
}
generated quantities {
  vector[n] ccf_marg_exp;
  for (i in 1:n) ccf_marg_exp[i] = Pi*theta[i] + (1-Pi)*mu[i];
  ...
}
```