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Multi-State Delinquency Models with Random Effects for Credit Cards

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Repayment state at time $t=\tau$

$\tau > s$

Repayment state
at time $t=s$

	0	1	2	3
0				
1				
2				
3				

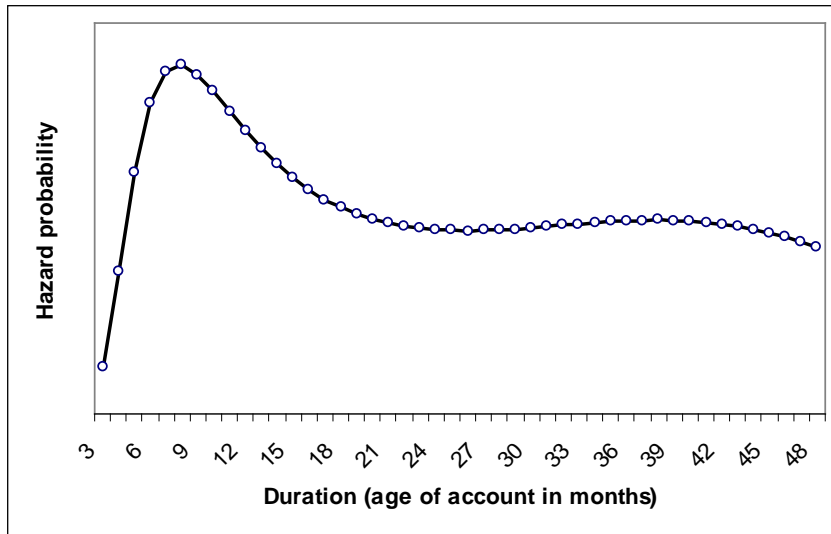
Three questions a lender tries to answer.

For any account i :

Q1. What is the probability of moving from up to date (0) to 3 behind, any time in the first T months ?

Q2. What is the probability of moving from state 2 to state 3 in the next month, given that it has not been in state 3 before?

Q3. What is the probability of moving from state h to state j between month s and month τ ?



Example

$$\lambda_i(t, \mathbf{x}_i(t)) = \lambda_0(t) \cdot \exp(\boldsymbol{\beta}^T \mathbf{x}_i(t))$$

Advantages over static models

- Likelihood function incorporates censored cases
- Do not have to pre-define observation window (can predict for any duration time period)
- Can incorporate time varying covariates



Two State Intensity (Survivor) Models of Default

Consumer: Banasik, Crook, Thomas (1999), Stepanova & Thomas (2002), Andreeva, Ansell, Crook (2005), Bellotti & Crook (2009, 2012, 2013), Djeundje & Crook (2017)

Corporates: Shumway (2001), Duffie (2011) Creal et al (2014)



Markov Chains

Ho et al (2004), Malik & Thomas (2012)

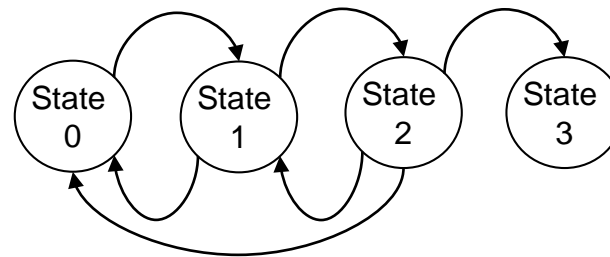
Multi-state Intensity Models

Methodology: Andersen et al (1993), Gagliardini & Gouriéroux (2005)

Consumer: Leow & Crook (2014) Leow & Crook (2015) Djeundje & Crook (2017)

Corporates: Jarrow et al (1997), Lando & Skødeberg (2002), Duffie et al (2007), Kadam & Lenk (2008), Stefanescu (2009), Figlewski et al (2012), Koopman (2009), Creal et al (2014)

- Four states defined: 0, 1, 2, 3, according to number of months in arrears



$$\alpha_{hji}(t) = \frac{P(T_i \in [t, t + dt] | T_i \geq t)}{dt}$$

$$\alpha_{hji}(t) = Y_{hi}(t) \alpha_{hj0}(t) \exp\{ \boldsymbol{\beta}_{hj}^T \mathbf{X}_i(t) \}$$

Continuous time

Indicator for whether individual i was in state h at time τ

Baseline transition intensity for state h to state j at time τ

Vector of unknown regression coefficients

Vector of covariates for individual i

$$p_{hjit_\alpha} = F_{hj}^L \{ g_{hj}(t_\alpha) + \boldsymbol{\beta}_{hj}^T \mathbf{x}_{it_\alpha} \}$$

Discrete time

So far P_{hjit} represents probability that case i in state h will jump to j assuming j is the only state it can jump to.

Now include competing states i can move to (e.g. state 1 to 0 or 1 to 2 or 1 to 1).

2 Methods:

- Estimate **transition intensities**, form **generator matrix of integrated intensities**, compute competing probabilities using **product integral** (Leow & Crook: 2014, Leow & Crook: 2015, Lando & Skødeberg: 2002)
- **Directly from transition probabilities** (Promislow: 2006, Luptakova & Bilikova: 2014), Dickson et al : 2009) – we follow here

Reason: computing time extremely large when estimating and including frailty using first method.



Two innovations

- Include random effects
- Use highly flexible function for baseline: B-Splines

Include random effects

Replace $\Pr(d_{it_\alpha} = 1 | \mathbf{x}_i) = p_{it_\alpha} = F^L(g(t_\alpha) + \mathbf{x}_{it}^T \boldsymbol{\beta} + e_i)$ $e_i \sim N(0, \sigma^2)$

by $\Pr(J_{hjit_\alpha} = 1 | \mathbf{x}_i) = p_{hjit_\alpha} = F_{hj}^L(g_{hj}(t_\alpha) + \mathbf{x}_{it}^T \boldsymbol{\beta}_{hj} + e_{hji})$ $e_{hji} \sim N(0, \sigma_{hj}^2)$

Notice t is duration time.

Flexible base line

Use B-splines for $g_{hj}(t_\alpha)$

$$g_{hj}(t_\alpha) = \sum_{l=1}^c B_l(t) \mathbf{b}_{l,hj}$$

where $B_l(t)$ are B-spline functions at points t and $\mathbf{b}_{hj} = (b_1, \dots, b_c)$ is a vector of unknown coefficients to be estimated

We wish to estimate

$$\boldsymbol{\beta}_{hj}, \mathbf{b}_{hj}, \boldsymbol{\sigma}_{hj}$$

Let

$$\mathbf{Y} = (Y_{hj,i}, (hj), i) \quad \text{where} \quad Y_{hj,i}(t) = \begin{cases} 1 & \text{if account } i \text{ is in state } j \text{ at time } t, \text{ given it was in } h \text{ at } t-1 \\ 0 & \text{if account } i \text{ is in state } h \text{ at time } t, \text{ given it was in } h \text{ at } t-1 \end{cases}$$

$$\boldsymbol{\beta} = (\beta_{hj}, (h, j))$$

$$\mathbf{u} = (u_{hj,i}(h, j), i)$$

ϕ_u = multivariate normal density

Joint likelihood of (\mathbf{Y}, \mathbf{u}) is

$$L_{(\mathbf{Y}, \mathbf{u})} = (\boldsymbol{\beta}, \mathbf{b}, \boldsymbol{\sigma}) = L_{(\mathbf{Y}|\mathbf{u})}(\boldsymbol{\beta}, \mathbf{u}) \times \phi_u(\boldsymbol{\sigma}) \quad \text{where} \quad \phi_u(\boldsymbol{\sigma}) \propto |\boldsymbol{\sigma}|^{-0.5} \exp\left(-\frac{1}{2} \mathbf{u}^T \boldsymbol{\sigma}^{-1} \mathbf{u}\right)$$

and

$$L_{(\mathbf{Y}|\mathbf{u})} = (\boldsymbol{\beta}, \mathbf{b}, \boldsymbol{\sigma}) = \prod_{(h,j)} \prod_t \prod_{i \in \mathfrak{R}_{h,j}(t)} [p_{hji}(t)]^{y_{hji}(t)} \times [1 - p_{hji}(t)]^{1 - y_{hji}(t)}$$

$\mathfrak{R}_{hj(t)}$ = risk set for transitions from h to j at t .

We wish to maximise the marginal likelihood

$$\text{Max}_{\boldsymbol{\beta}, \mathbf{b}} L_{(\mathbf{Y})}(\boldsymbol{\beta}, \mathbf{b}, \boldsymbol{\sigma}) = \text{Max}_{\boldsymbol{\beta}, \mathbf{b}} \int L_{(\mathbf{Y}, \mathbf{u})}(\boldsymbol{\beta}, \mathbf{b}, \boldsymbol{\sigma}) d\mathbf{u}$$

$$\tilde{p}_{hji}(t) = p_{hji}(t) \times \left(1 - \frac{1}{2} \sum_{\substack{k \neq j \\ \text{where} \\ (h,k) \in \varnothing}} p_{hji}(t) + \frac{1}{3} \sum_{\substack{k \neq r \neq j \\ \text{where} \\ (h,k) \in \varnothing \\ (h,r) \in \varnothing}} p_{hki}(t) p_{hri}(t) - \frac{1}{4} \sum_{\substack{\text{where} \\ (h,k) \in \varnothing \\ (h,r) \in \varnothing \\ (h,s) \in \varnothing}} p_{hki}(t) p_{hri}(t) p_{hsi}(t) + \dots \right)$$

$$\tilde{\mathbf{P}}_i(t) = \begin{bmatrix} (1 - \tilde{p}_{01,i}(t)) & \tilde{p}_{01,i}(t) & 0 & 0 \\ \tilde{p}_{10,i}(t) & (1 - \tilde{p}_{10,i}(t) - \tilde{p}_{12,i}(t)) & \tilde{p}_{12,i}(t) & 0 \\ \tilde{p}_{20,i}(t) & \tilde{p}_{21,i}(t) & 1 - \tilde{p}_{20,i}(t) - \tilde{p}_{21,i}(t) - \tilde{p}_{23,i}(t) & \tilde{p}_{23,i}(t) \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Probs that account i in state $\delta_i(t_1)$ at time t_1 will be in state 0, 1, 2, or 3 at time t_2 are elements in following vector, $\boldsymbol{\mu}(t_2)$, given by the matrix product

$$\boldsymbol{\mu}(t_2) = [\mathbf{1}_{\{\delta_i(t_1)=0\}}, \mathbf{1}_{\{\delta_i(t_1)=1\}}, \mathbf{1}_{\{\delta_i(t_1)=2\}}, \mathbf{1}_{\{\delta_i(t_1)=3\}}] \tilde{\mathbf{P}}_i(t_1, t_2)$$

where $\mathbf{1}$ denotes indicator operator

$$\tilde{\mathbf{P}}_i(t_1, t_2) \text{ represents the cumulative transition prob matrix given by } \tilde{\mathbf{P}}_i(t_1, t_2) = \prod_{t=t_1+1}^{t_2} \tilde{\mathbf{P}}_i(t)$$

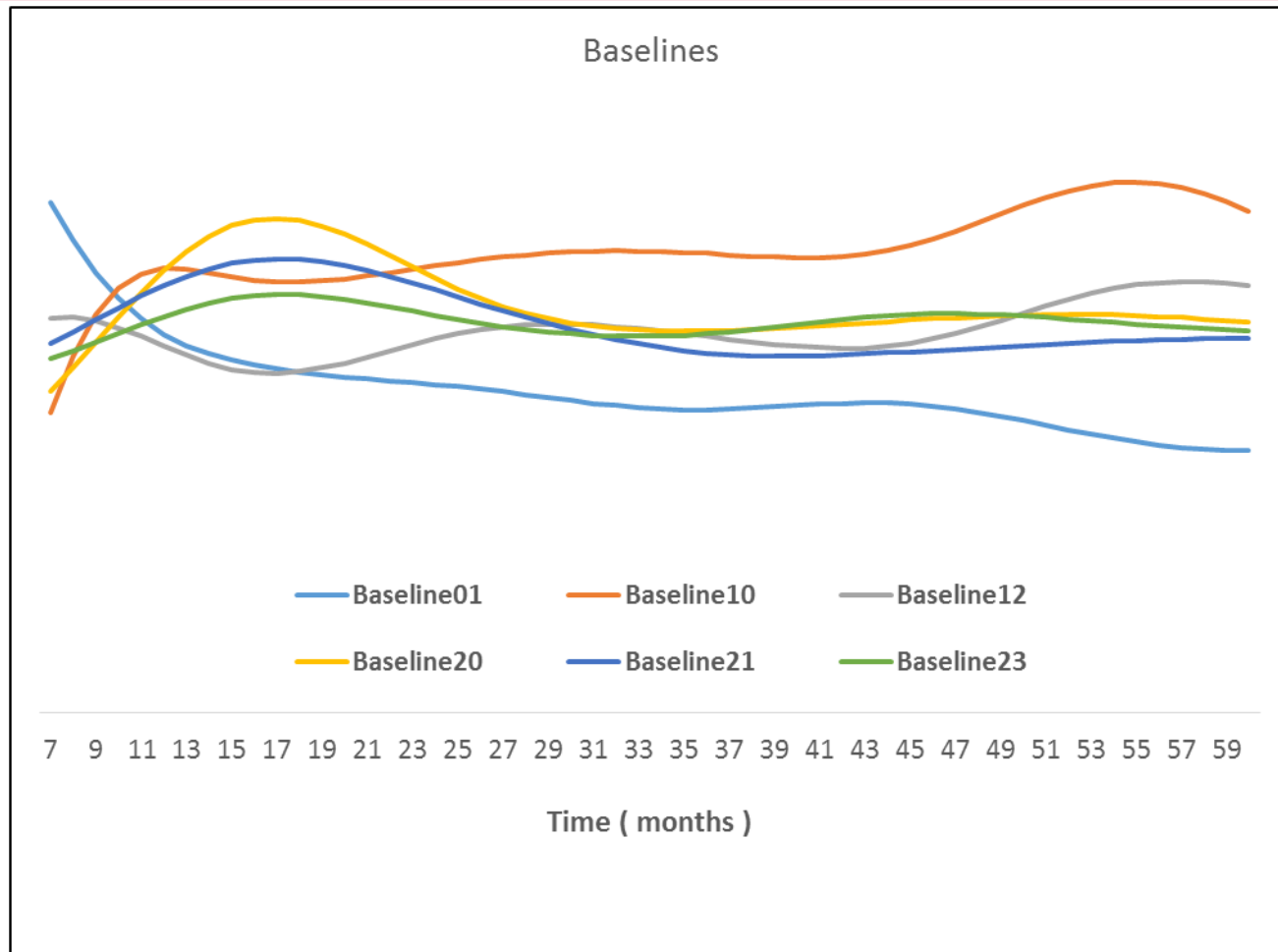


Credit card accounts tracked monthly

- Application variables
- Behavioural indicators e.g. spending amount, repayment amount (if any)
- Macroeconomic variables



Results



Variable	Delinquency type			Recovery type		
	T 01	T 12	T 23	T 10	T 21	T 20
Number of cards	n	n	n	-	n	n
Landline Y/N	n	-	n	-	n	n
Time at address	n	n	-	n	-	n
Time with bank	-	-	-	+	n	n
Time with bank, missing	n	n	n	+	n	n
Income, ln	n	+	n	+	n	n
Income, missing	-	+	n	+	n	n
Housing type (categorical)	+	+	n	n	n	n
Age group (categorical)	-	-	n	n	n	n
Employment status (categorical)	Mixed			Mixed		
Credit limit, ln, lag6	+	-	n	-	-	n
Repayment amt, ln, lag6	+	n	-	+	n	+
Proportion of credit drawn, lag6	+	n	n	-	-	-

Variable	Delinquency type			Recovery type		
	T 01	T 12	T 23	T 10	T 21	T 20
Rate of total jumps, lag6	+	+	n	-	+	+
Improvement in state from 3 months previous, lag6	-	+	n	n	n	n
RPI, NSA, lag6	+	n	n	-	n	-
AWE, NSA, lag6	+	n	n	n	-	n
FTSE, NSA, lag6	+	n	+	n	n	n
Unemployment rate, SA, lag6	n	-	n	-	n	n
IOP, NSA, lag6	-	n	-	n	n	n
HPI, SA, lag6	-	n	n	+	n	+
Consumer confidence, NSA, lag6	n	n	n	-	n	-
Credit card IR, NSA, lag6	-	n	-	n	n	-
Mortgage loan IR, NSA, lag6	+	n	n	-	n	n
Total credit outstanding, ln, NSA, lag6	-	n	n	+	+	+



Jump	01	10	12	20	21	23
σ_{hj}^2	1.14	1.59	0.98	2.36	1.78	1.94

Deviance residuals all within 2 sds of mean for (virtually) all time periods for all transitions

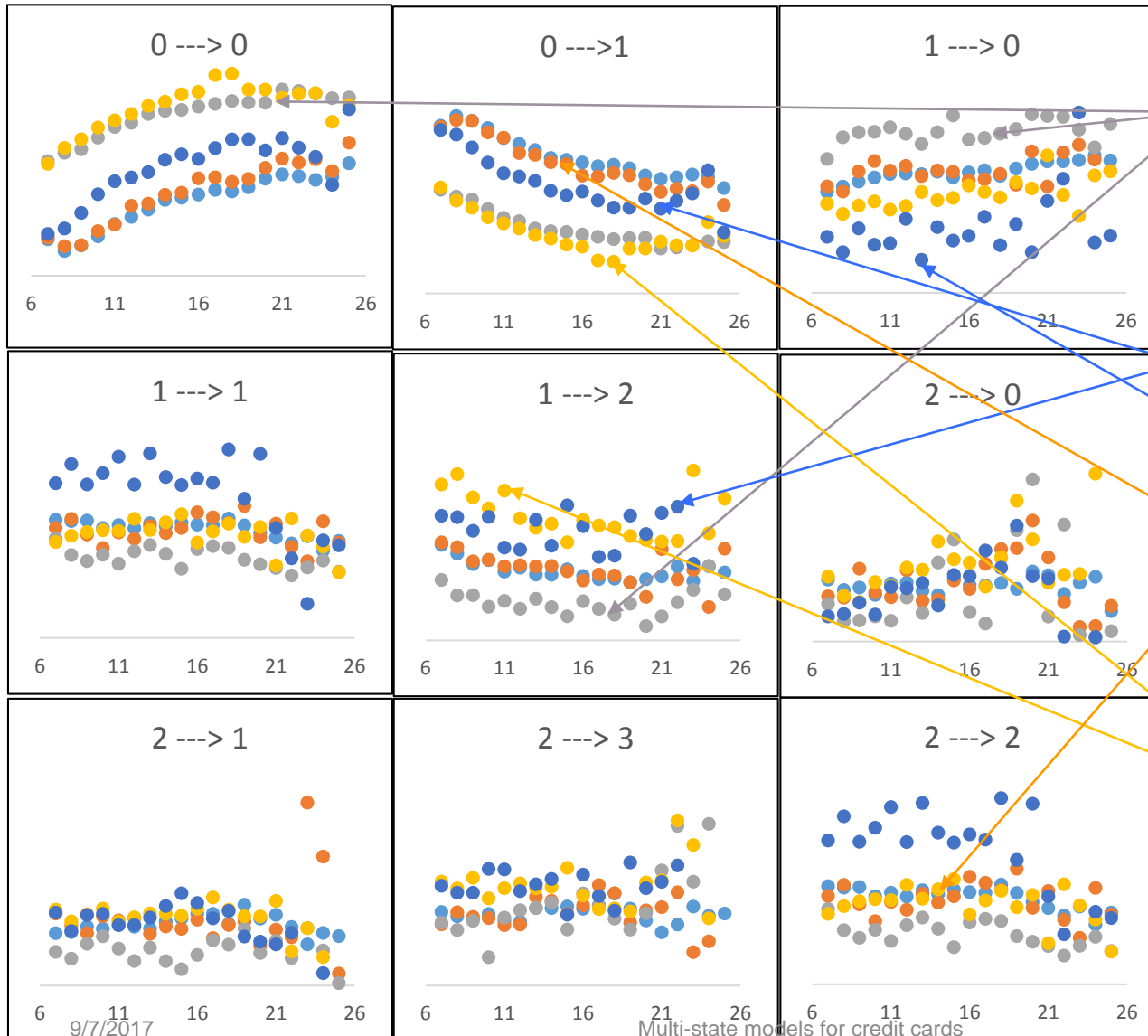


Use test set (accounts opened 2008 onwards)

For a given value of a covariate eg age, for each account for each transition type $(h, j) \in \mathcal{S}$

- simulate values of a random deviate u_{hji} from $N(0, \hat{\sigma}_{hj}^2)$ where σ_{hj} are from the estimd eqtns
- add to linear predictor of $p_{hj,i}(t)$ to get $\hat{p}_{hj,i}(t)$
- for each t take average over i
- Repeat for each value of the covariate

Predicting transition probabilities by employment category



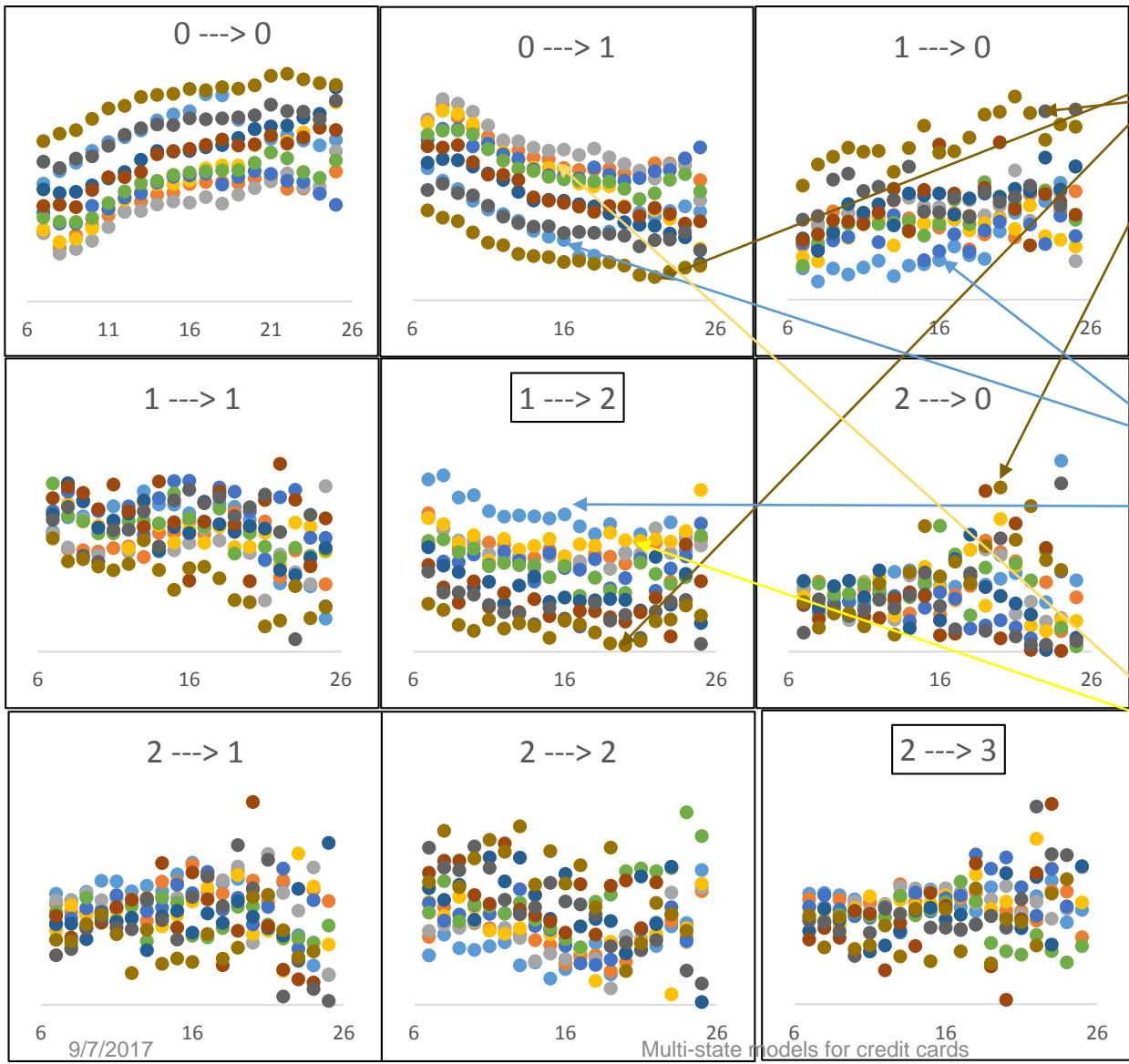
Retired, Unemployed (grey) low chance of bec more del, high chance of recovering.

Employed (dk blue) av chance miss 1, high chance missing further. Low chance recover from 1

Self Empl (orange) high chance miss 1, average chance miss more, low chance move to 3, high chance recover.

Students (yellow) low chance miss one, if do high chance move to 2 and from 2 to 3

Predicting transition probabilities by age at application



Older (brown) less likely to miss 1, or 2, most likely to recover

Youngest (light blue) less likely to miss 1, if do least likely to recover and more likely to move to 2

Young (yellow) more to miss 1 then 2 then 3. Least likely to recover from 1 or 2



Cumulative transition probability matrix, $P(6,12)$, by employment type for typical account opened in January 2009

		To state				
		0	1	2	3	
Employment A	From state	0	0.9020	0.0634	0.0167	0.0179
		1	0.7703	0.0591	0.0242	0.1463
		2	0.3361	0.0333	0.0256	0.6051
		3	0	0	0	1
Employment B	From state	0	0.9040	0.0595	0.0198	0.0167
		1	0.7569	0.0572	0.0357	0.1501
		2	0.3207	0.0365	0.0470	0.5958
		3	0	0	0	1
Employment C	From state	0	0.8960	0.0561	0.0207	0.0272
		1	0.7080	0.0497	0.0290	0.2133
		2	0.2489	0.0242	0.0260	0.7009
		3	0	0	0	1
Employment D	From state	0	0.9698	0.0235	0.0034	0.0032
		1	0.8983	0.0246	0.0123	0.0648
		2	0.3529	0.0213	0.0424	0.5834
		3	0	0	0	1
Employment E	From state	0	0.9351	0.0287	0.0110	0.0252
		1	0.7021	0.0241	0.0113	0.2625
		2	0.3099	0.0123	0.0071	0.6708
		3	0	0	0	1

$\tilde{\mathbf{P}}_i(t_1, t_2)$ represents the cumulative transition prob matrix given by $\tilde{\mathbf{P}}_i(t_1, t_2) = \prod_{t=t_1+1}^{t_2} \tilde{\mathbf{P}}_i(t)$

Let $\hat{p}_{ik0}, \hat{p}_{ik1}, \hat{p}_{ik2}, \hat{p}_{ik3}$ denote predicted competing probabilities that an account will be in state 0, 1, 2, 3 at time t_2 given it was in state k at t_1 that is the elements in row k in $\tilde{\mathbf{P}}_i(t_1, t_2)$

To predict state need to compare predicted probabilities with cut off.

At t_2 we predict account i will be in state j such that

$$\hat{p}_{kj} - c_{kj} = \max\{p_{k0} - c_{k0}, p_{k1} - c_{k1}, p_{k2} - c_{k2}, p_{k3} - c_{k3}\}$$

where

$c_{k0}, c_{k1}, c_{k2}, c_{k3}$ as the multidimensional maximisers of f_k where

$$f_k(a_0, a_1, a_2, a_3) = \frac{1}{N_k(t_1)} \sum_{\substack{i, \\ \text{with} \\ \delta_i(t_1)=k}} 1_{\{\delta_i(t_2|a_0, a_1, a_2, a_3)=\delta_{it_2}\}}$$

Standardised discrepancy

$$\frac{\hat{p}_{kj} - c_{kj}}{\hat{s}_{kj}} = \max \left\{ \frac{\hat{p}_{k0} - c_{k0}}{\hat{s}_{k0}}, \frac{\hat{p}_{k1} - c_{k1}}{\hat{s}_{k1}}, \frac{\hat{p}_{k2} - c_{k2}}{\hat{s}_{k2}}, \frac{\hat{p}_{k3} - c_{k3}}{\hat{s}_{k3}} \right\}$$

Cumulative discrepancy

$$\frac{\hat{p}_{kj} - c_{kj}}{c_{kj}} = \max \left\{ \frac{\hat{p}_{k0} - c_{k0}}{c_{k0}}, \frac{\hat{p}_{k1} - c_{k1}}{c_{k1}}, \frac{\hat{p}_{k2} - c_{k2}}{c_{k2}}, \frac{\hat{p}_{k3} - c_{k3}}{c_{k3}} \right\}$$

Prediction accuracy at time 12, given state at time 6 (%)

State at time 6	No random effects			With random effects		
	discrepancy	stand. discrepancy	relative discrepancy	discrepancy	stand. discrepancy	relative discrepancy
0	89	90	89	90	90	90
1	72	73	72	72	72	72
2	63	62	62	63	63	63



Survival models are the **second** generation of credit scoring models.

Multistate intensity models are the **third** generation.

Multistate intensity models yield predictions of transition probabilities between delinquency states. They are useful for IFRS9, the prediction of provisions and for economic capital prediction.

Including frailty in multistate intensity models

- substantially increases estimation times so need to move from continuous time models to discrete time models
- alters coefficients noticeably and renders many covariates measured for each account insignificant
- leads macroeconomic variables to be significant
- Increases prediction accuracy.

Use of B-splines gives more accurate predictions than more restrictive baseline functions.